

Non-thermal particles

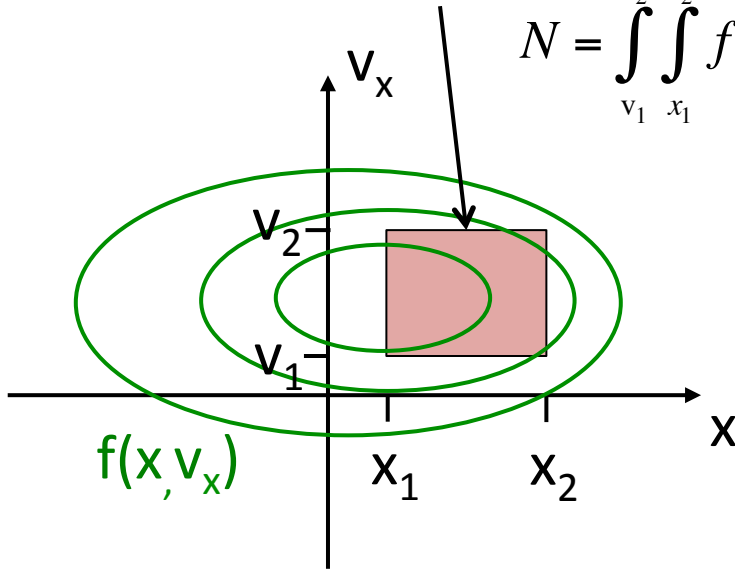
The Fokker-Planck equation

Lecture 18

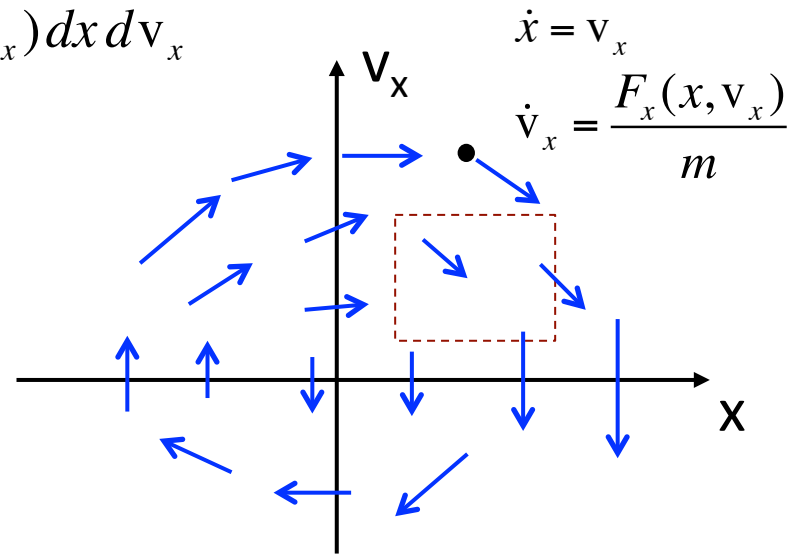
March 29, 2017

particles in phase-space volume:

$$N = \int_{v_1}^{v_2} \int_{x_1}^{x_2} f(x, v_x) dx dv_x$$

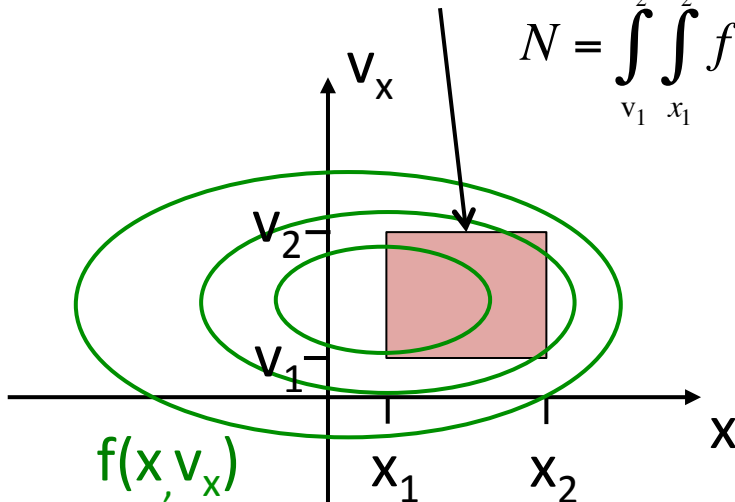


particles “flow” through phase-space

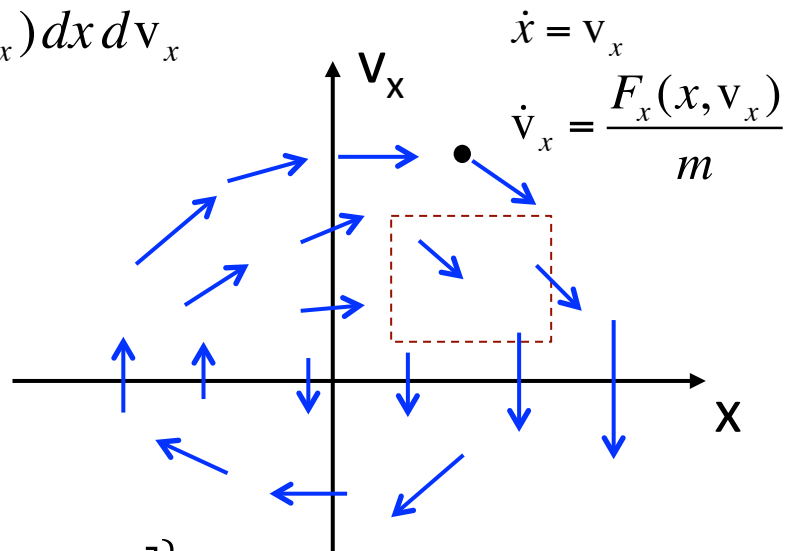


particles in phase-space volume:

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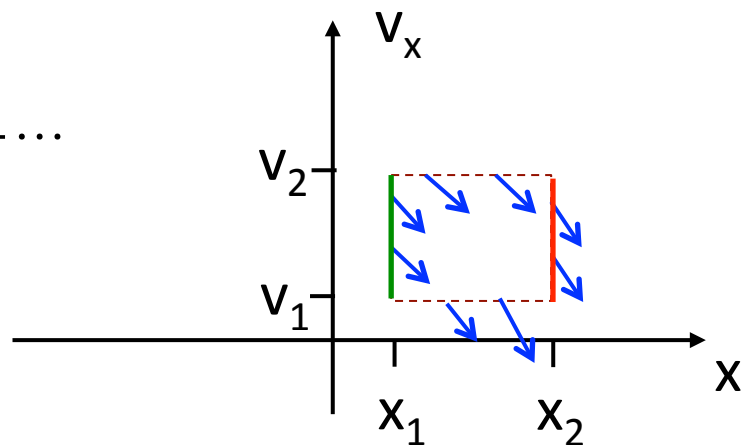
particles "flow" through phase-space



$$\frac{dN}{dt} = \int \frac{\partial f}{\partial t} dx dv_x = - \int \left\{ \frac{\partial}{\partial x} (v_x f) + \frac{\partial}{\partial v_x} \left[\frac{F_x(x, v_x)}{m} f \right] \right\} dx dv_x$$

$$= - \int_{v_1}^{v_2} \left[\underbrace{v_x f(x_2, v_x)}_{\text{out}} - \underbrace{v_x f(x_1, v_x)}_{\text{in}} \right] dv_x + \dots$$

$$\boxed{\frac{\partial f}{\partial t} = - \frac{\partial}{\partial x} (v_x f) - \frac{\partial}{\partial v_x} \left[\frac{F_x(x, v_x)}{m} f \right]}$$



Vlasov's equation

1d version

$$\frac{\partial f}{\partial t} = -\frac{\partial}{\partial x}(v_x f) - \frac{\partial}{\partial v_x} \left[\frac{F_x(x, v_x)}{m} f \right]$$

3d version

$$\frac{\partial f_\sigma}{\partial t} = -\sum_i \frac{\partial}{\partial x_i} (v_i f_\sigma) - \sum_i \frac{\partial}{\partial v_i} \left[\frac{F_i(\mathbf{x}, \mathbf{v})}{m} f_\sigma \right] = -\frac{\partial}{\partial x_i} (v_i f_\sigma) - \frac{\partial}{\partial v_i} \left[\frac{F_i(\mathbf{x}, \mathbf{v})}{m} f_\sigma \right]$$

$\sigma = p, e$ (proton, electron)

Implicit sum over repeated indices

Force: $\mathbf{F}(\mathbf{x}, \mathbf{v}) = q_\sigma \mathbf{E}(\mathbf{x}) + q_\sigma \frac{\mathbf{v}}{c} \times \mathbf{B}(\mathbf{x})$

$$\nabla \times \mathbf{B} = \frac{4\pi}{c} \mathbf{J}(\mathbf{x}) = \frac{4\pi e}{c} \int [\mathbf{v} f_p(\mathbf{x}, \mathbf{v}) - \mathbf{v} f_e(\mathbf{x}, \mathbf{v})] d^3 \mathbf{v} \quad \& \text{ similarly for } \mathbf{E}(\mathbf{x})$$

$\mathbf{E}(\mathbf{x})$ & $\mathbf{B}(\mathbf{x})$ are each linear in $f_p(\mathbf{x}, \mathbf{v})$ & $f_e(\mathbf{x}, \mathbf{v})$

Q: what about the **pressure force**? Does that need to be included in F_i ? How?

Vlasov's equation

1d version

$$\frac{\partial f}{\partial t} = -\frac{\partial}{\partial x}(v_x f) - \frac{\partial}{\partial v_x} \left[\frac{F_x(x, v_x)}{m} f \right]$$

3d version

$$\frac{\partial f_\sigma}{\partial t} = -\sum_i \frac{\partial}{\partial x_i} (v_i f_\sigma) - \sum_i \frac{\partial}{\partial v_i} \left[\frac{F_i(\mathbf{x}, \mathbf{v})}{m} f_\sigma \right] = -\frac{\partial}{\partial x_i} (v_i f_\sigma) - \frac{\partial}{\partial v_i} \left[\frac{F_i(\mathbf{x}, \mathbf{v})}{m} f_\sigma \right]$$

$\sigma = p, e$ (proton/electron)

Implicit sum over repeated indices

Force: $\mathbf{F}(\mathbf{x}, \mathbf{v}) = q_\sigma \mathbf{E}(\mathbf{x}) + q_\sigma \frac{\mathbf{v}}{c} \times \mathbf{B}(\mathbf{x})$

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$\mathbf{E}(\mathbf{x})$ & $\mathbf{B}(\mathbf{x})$ are each linear in $f_p(\mathbf{x}, \mathbf{v})$ & $f_e(\mathbf{x}, \mathbf{v})$

→ Vlasov equations for $f_p(\mathbf{x}, \mathbf{v})$ & $f_e(\mathbf{x}, \mathbf{v})$
 – **nonlinear** in $f_p(\mathbf{x}, \mathbf{v})$ & $f_e(\mathbf{x}, \mathbf{v})$

Vlasov's equation

$$\frac{\partial f_\sigma}{\partial t} + \frac{\partial}{\partial x_i} (v_i f_\sigma) + \frac{\partial}{\partial v_i} \left[\frac{F_i(\mathbf{x}, \mathbf{v})}{m} f_\sigma \right] = 0 \quad \mathbf{F}(\mathbf{x}, \mathbf{v}) = q_\sigma \mathbf{E}(\mathbf{x}) + q_\sigma \frac{\mathbf{v}}{c} \times \mathbf{B}(\mathbf{x})$$

$f_\sigma(\mathbf{x}, \mathbf{v})$ = **smoothed** phase space density – does not reflect discrete particles – represents an **ensemble average**

→ $\mathbf{E}(\mathbf{x})$ & $\mathbf{B}(\mathbf{x})$ are smooth/ensemble averaged fields – not fields from discrete particles. Particles at ~same point in space feel ~same force

What is **not** included:

Forces between particles @ ~same point – i.e. **collisions**

Vlasov eqs. = eqs. for a **collisionless** plasma

Including Collisions: Fokker-Planck

$$\frac{\partial f_\sigma}{\partial t} + \frac{\partial}{\partial x_i} (v_i f_\sigma) + \frac{\partial}{\partial v_i} \left[\frac{F_i(\mathbf{x}, \mathbf{v})}{m} f_\sigma \right] = \left(\frac{\partial f_\sigma}{\partial t} \right)_{\text{col}} = - \frac{\partial}{\partial v_i} \left(\left\langle \frac{\Delta v_i}{\Delta t} \right\rangle f_\sigma \right) + \frac{1}{2} \frac{\partial^2}{\partial v_i \partial v_j} \left(\left\langle \frac{\Delta v_i \Delta v_j}{\Delta t} \right\rangle f_\sigma \right)$$

$$\left\langle \frac{\Delta v_i}{\Delta t} \right\rangle \quad \& \quad \left\langle \frac{\Delta v_i \Delta v_j}{\Delta t} \right\rangle$$

are ensemble-average changes
due to fluctuating **E** & **B** fields.*

Each depends on **v** – velocity

@ t – Δt prior to fluctuating forces

dependence
captured in
functions

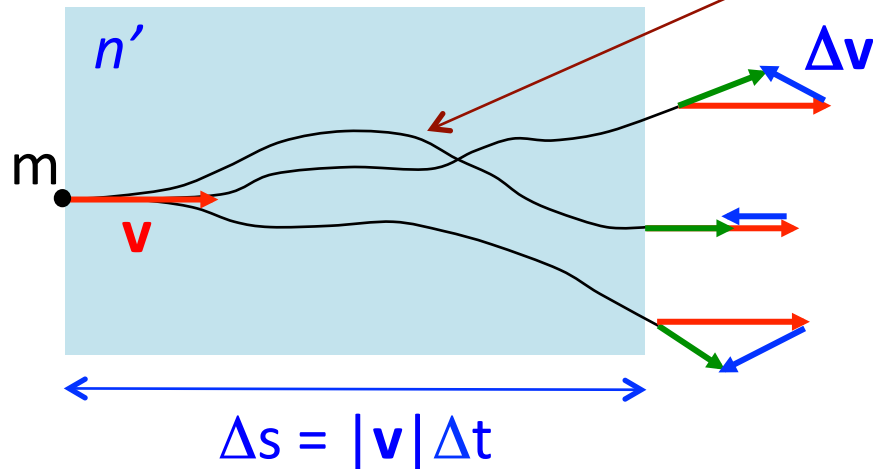
$$D_{ij}(\mathbf{v}) = \frac{1}{2} \left\langle \frac{\Delta v_i \Delta v_j}{\Delta t} \right\rangle \quad A_i(\mathbf{v}) = \left\langle \frac{\Delta v_i}{\Delta t} \right\rangle - \frac{\partial D_{ij}}{\partial v_j}$$

$$\frac{\partial f_\sigma}{\partial t} + \frac{\partial}{\partial x_i} (v_i f_\sigma) + \frac{\partial}{\partial v_i} \left[\frac{F_i}{m} f_\sigma \right] = \left(\frac{\partial f_\sigma}{\partial t} \right)_{\text{col}} = - \frac{\partial}{\partial v_i} [A_i(\mathbf{v}) f_\sigma] + \frac{\partial}{\partial v_i} \left[D_{ij}(\mathbf{v}) \frac{\partial f_\sigma}{\partial v_j} \right]$$

Fokker-Planck equation

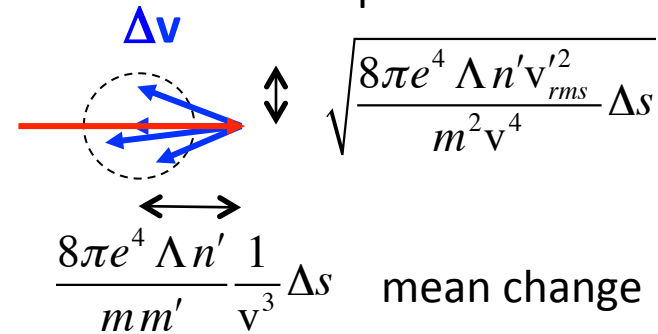
*same eqs. used for stellar dynamics: “collision” from gravitational interaction

scatterers of mass: m' ,
 r.m.s. velocity: $v'_{rms} \ll |\mathbf{v}|$



many small-angle deflections – add up to random change $\Delta \mathbf{v}$

random walk:
 displacement $\sim t^{1/2}$



$$\left\langle \frac{\Delta v_i}{\Delta t} \right\rangle = -\frac{8\pi e^4 \Lambda n'}{m m'} \frac{v_i}{v^3} \quad \left\langle \frac{\Delta v_i \Delta v_j}{\Delta t} \right\rangle = \frac{8\pi e^4 \Lambda n' v'^2_{rms}}{m^2} \frac{\delta_{ij}}{v^3}$$

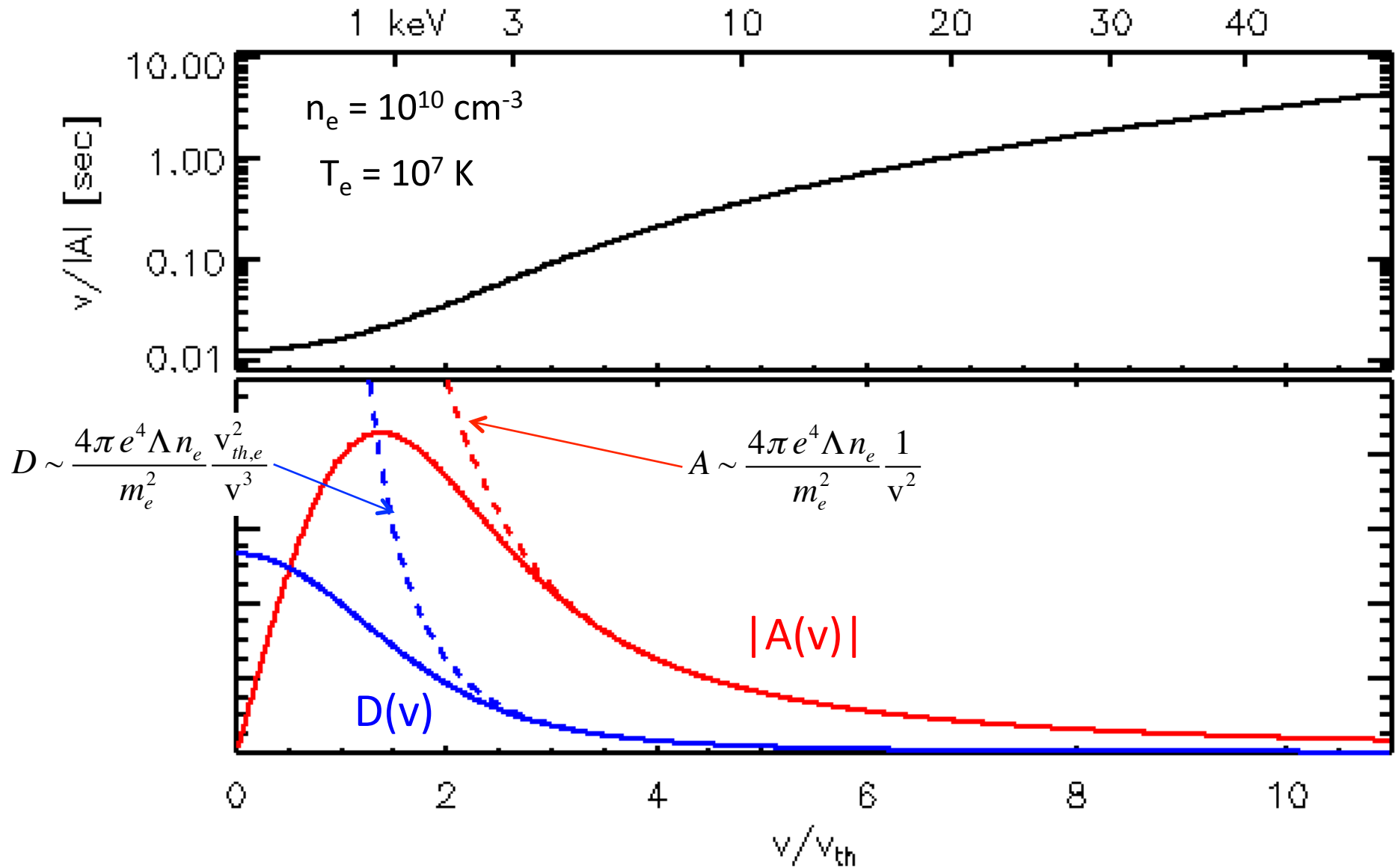
$$A_i(\mathbf{v}) = -\frac{4\pi e^4 \Lambda n'}{m m'} \frac{v_i}{v^3}$$

$$D_{ij}(\mathbf{v}) = \frac{4\pi e^4 \Lambda n' v'^2_{rms}}{m^2} \frac{\delta_{ij}}{v^3}$$

each is linear in $f_{\sigma'}(\mathbf{x}, \mathbf{v})$ – $\sigma' =$ target species

Coulomb log Λ enters here – how many scatterers to include?

e^- / e^- collisions ($\sigma = \sigma' = e$) w/ $f_e(\mathbf{v})$ Maxwellian:

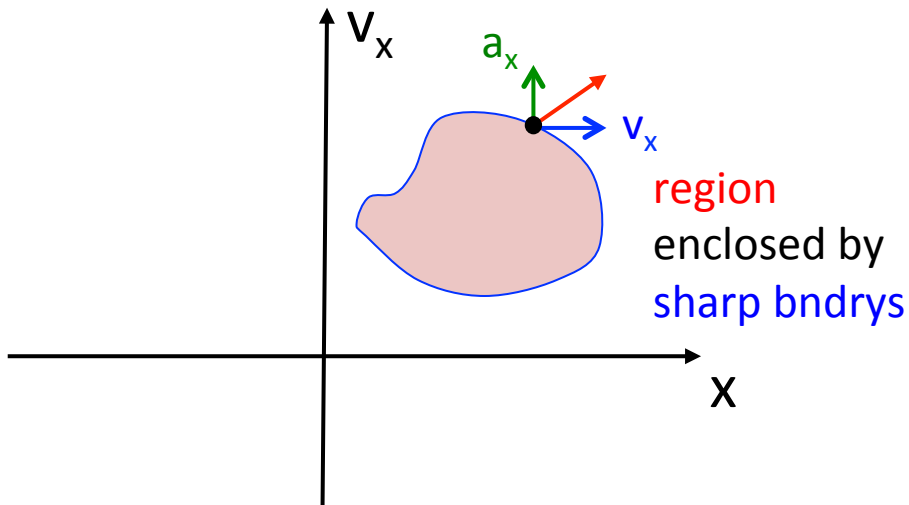


What it really means

$$\frac{\partial f}{\partial t} + \frac{\partial}{\partial x_i} (v_i f) + \frac{\partial}{\partial v_i} \left[\underbrace{\left(\frac{F_i}{m} + A_i \right)}_{\text{acceleration } a_i} f \right] = \frac{\partial}{\partial v_i} \left[\cancel{D_{ij}(\mathbf{v})} \frac{\partial f}{\partial v_j} \right] = 0$$

velocity acceleration a_i

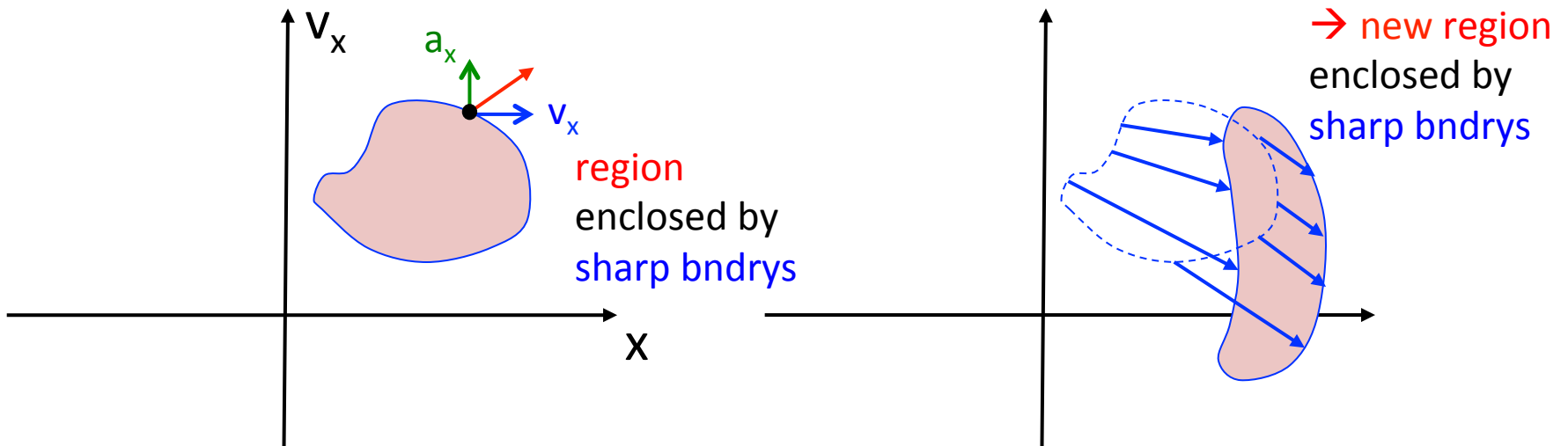
what happens w/o this term?



What it really means

$$\frac{\partial f}{\partial t} + \frac{\partial}{\partial x_i} (v_i f) + \frac{\partial}{\partial v_i} \left[\underbrace{\left(\frac{F_i}{m} + A_i \right)}_{\text{acceleration } a_i} f \right] = \frac{\partial}{\partial v_i} \left[\cancel{D_{ij}(\mathbf{v})} \frac{\partial f}{\partial v_j} \right] = 0$$

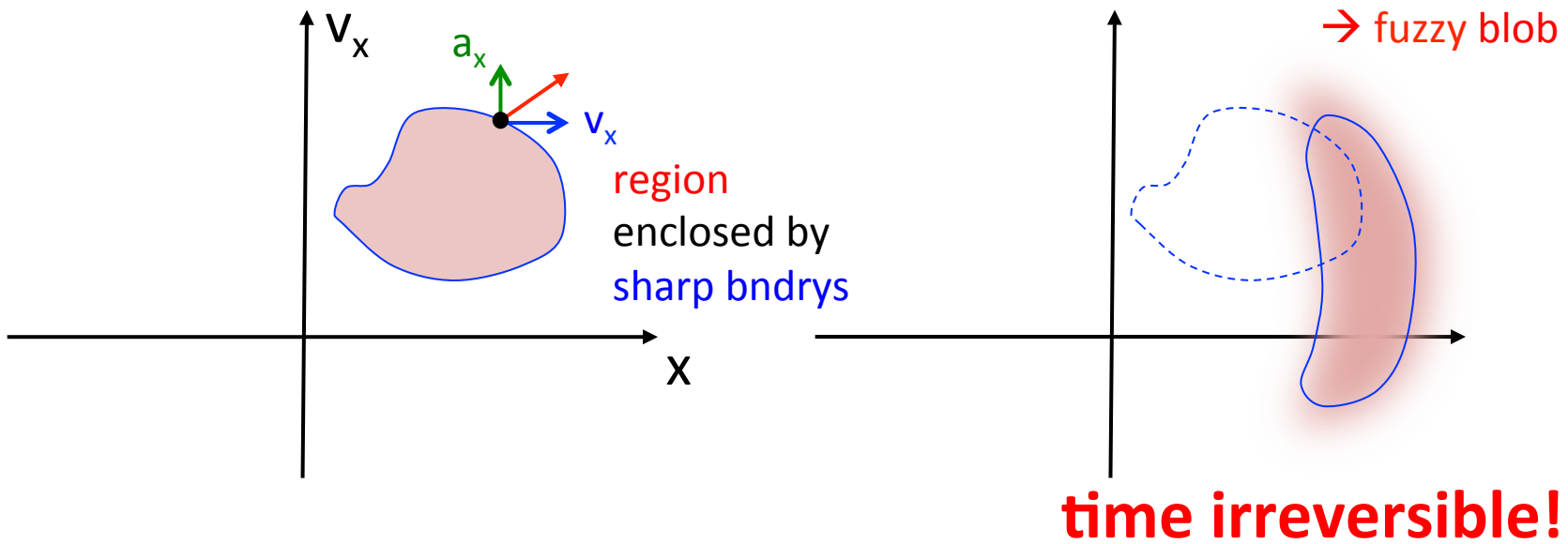
velocity acceleration a_i what happens w/o this term?



pure advection in phase space: evolution maps
sharp bndrys → sharp bndrys

What it really means

$$\frac{\partial f}{\partial t} + \underbrace{\frac{\partial}{\partial x_i} (v_i f) + \frac{\partial}{\partial v_i} \left[\left(\frac{F_i}{m} + A_i \right) f \right]}_{\text{phase-space advection}} = \underbrace{\frac{\partial}{\partial v_i} \left[D_{ij}(\mathbf{v}) \frac{\partial f}{\partial v_j} \right]}_{\text{diffusive term}}$$



advection/diffusion: $D_{ij}(\mathbf{v})$ is **diffusion coefficient** –
 diffuses only in \mathbf{v} & conserves total integral = $n(\mathbf{x})$

$$\frac{\partial f}{\partial t} + \frac{\partial}{\partial x_i} (v_i f) + \frac{\partial}{\partial v_i} \left[\left(\frac{F_i}{m} + A_i \right) f \right] = \frac{\partial}{\partial v_i} \left[\boxed{D_{ij}(\mathbf{v})} \frac{\partial f}{\partial v_j} \right]$$

$D_{ij}(\mathbf{v})$ **velocity diffusion coefficient** [cm²/s⁻³]

- only diffuses in \mathbf{v}
- Random walk in \mathbf{v} due to numerous random accelerations – i.e. random “steps” in \mathbf{v}
- Compare to advection/diffusion of **spatial** field $\psi(\mathbf{x},t)$

$$\frac{\partial \psi}{\partial t} + \frac{\partial}{\partial x_i} [u_i(\mathbf{x}) \psi(\mathbf{x},t)] = \frac{\partial}{\partial x_i} \left[\boxed{\kappa_{ij}(\mathbf{x})} \frac{\partial \psi}{\partial x_j} \right] \rightarrow \kappa \nabla^2 \psi$$

- Diffusion coefficient $\kappa_{ij}(\mathbf{x}) \rightarrow \kappa$ [cm²/s⁻¹]
- Random walk in \mathbf{x} due to numerous random steps in \mathbf{x}
- Not present in Fokker-Planck eq. – no steps in \mathbf{x}

also time irreversible

What it really means

$$\left(\frac{\partial f}{\partial t}\right)_{\text{col}} = - \frac{\partial}{\partial v_i} \left[A_i(\mathbf{v}) f - D_{ij}(\mathbf{v}) \frac{\partial f}{\partial v_j} \right]$$

velocity-space divergence

$$n(\mathbf{x}) = \int f(\mathbf{x}, \mathbf{v}) d^3\mathbf{v}$$

Q: How do collisions affect density?

$$\left(\frac{\partial n}{\partial t}\right)_{\text{col}} = \int \left(\frac{\partial f}{\partial t}\right)_{\text{col}} d^3\mathbf{v} = - \int \frac{\partial}{\partial v_i} \left[A_i(\mathbf{v}) f - D_{ij}(\mathbf{v}) \frac{\partial f}{\partial v_j} \right] d^3\mathbf{v}$$

velocity-space
divergence
theorem



$$= - \oint_{|\mathbf{v}| \rightarrow \infty} \left[A_i(\mathbf{v}) f - D_{ij}(\mathbf{v}) \frac{\partial f}{\partial v_j} \right] da_i = 0$$

A: Leave it unchanged. Collisions are all at same point
– change particle velocities – leave their positions
unchanged

Q: How do collisions affect e^- momentum ?

$$P_{e,i} = m_e n_e u_{e,i} = m_e \int v_i f_e(\mathbf{x}, \mathbf{v}) d^3\mathbf{v}$$

$$\left(\frac{\partial f_e}{\partial t}\right)_{\text{col}} = -\frac{\partial}{\partial v_j} \left[\left\langle \frac{\Delta v_j}{\Delta t} \right\rangle f_e - \frac{1}{2} \frac{\partial}{\partial v_k} \left(\left\langle \frac{\Delta v_j \Delta v_k}{\Delta t} \right\rangle f_e \right) \right] \quad \text{Initial form of F-P eq.}$$

$$\left(\frac{\partial P_{e,i}}{\partial t}\right)_{\text{col}} = m_e \int v_i \left(\frac{\partial f_e}{\partial t}\right)_{\text{col}} d^3\mathbf{v} = -m_e \int v_i \frac{\partial}{\partial v_j} \left[\left\langle \frac{\Delta v_j}{\Delta t} \right\rangle f_e - \frac{1}{2} \frac{\partial}{\partial v_k} \left(\left\langle \frac{\Delta v_j \Delta v_k}{\Delta t} \right\rangle f_e \right) \right] d^3\mathbf{v}$$

velocity-space
integration
by parts



$$= m_e \int \delta_{ij} \frac{\partial v_i}{\partial v_j} \left[\left\langle \frac{\Delta v_j}{\Delta t} \right\rangle f_e - \frac{1}{2} \frac{\partial}{\partial v_k} \left(\left\langle \frac{\Delta v_j \Delta v_k}{\Delta t} \right\rangle f_e \right) \right] d^3\mathbf{v}$$

divergence thm

$$= m_e \int \left\langle \frac{\Delta v_i}{\Delta t} \right\rangle f_e d^3\mathbf{v} - \frac{m_e}{2} \oint_{|\mathbf{v}| \rightarrow \infty} \left\langle \frac{\Delta v_i \Delta v_k}{\Delta t} \right\rangle f_e da_k$$

A: Collisions lead to a **drag force density** on electrons

$$\left(\frac{\partial P_{e,i}}{\partial t}\right)_{\text{col}} = m_e \int \left\langle \frac{\Delta v_i}{\Delta t} \right\rangle f_e d^3\mathbf{v}$$

Collisional drag force

$$\left(\frac{\partial P_{e,i}}{\partial t}\right)_{\text{col}} = m_e \int \left\langle \frac{\Delta \mathbf{v}_i}{\Delta t} \right\rangle f_e d^3 \mathbf{v}$$

velocity change due to collisions suffered by electrons:

$$\left\langle \frac{\Delta \mathbf{v}_i}{\Delta t} \right\rangle = \underbrace{\left\langle \frac{\Delta \mathbf{v}_i}{\Delta t} \right\rangle_{ee}}_{\text{collisions of e-s w/ other e-s}} + \underbrace{\left\langle \frac{\Delta \mathbf{v}_i}{\Delta t} \right\rangle_{ep}}_{\text{collisions of e-s w/ protons}}$$

Newton's 3rd law

$$\left(\frac{\partial P_{e,i}}{\partial t}\right)_{\text{col}} = m_e \int \left\langle \frac{\Delta \mathbf{v}_i}{\Delta t} \right\rangle_{ee} f_e d^3 \mathbf{v} + m_e \int \left\langle \frac{\Delta \mathbf{v}_i}{\Delta t} \right\rangle_{ep} f_e d^3 \mathbf{v}$$

drag only from protons

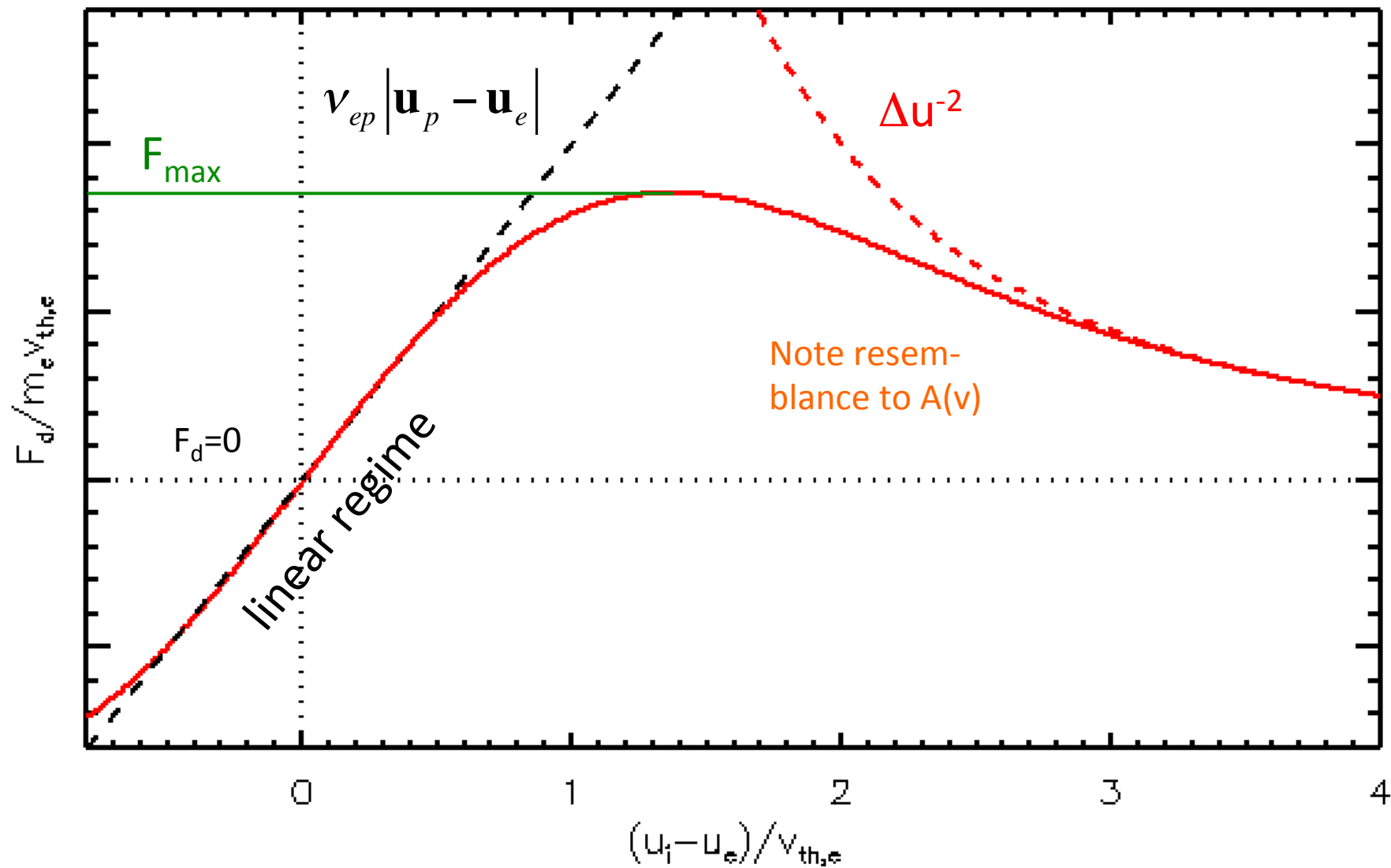
- expect drag to vanish if $\mathbf{u}_p = \mathbf{u}_e$
- lowest order in $|\mathbf{u}_p - \mathbf{u}_e| \ll v_{\text{th},e}$

collision freq. from doing integral

$$m_e \int \left\langle \frac{\Delta \mathbf{v}}{\Delta t} \right\rangle_{ep} f_e d^3 \mathbf{v} \approx m_e n_e \mathbf{v}_{ep} (\mathbf{u}_p - \mathbf{u}_e) \approx \frac{m_e}{e} \mathbf{v}_{ep} \mathbf{J}$$

$$\frac{1}{n_e} \int \left\langle \frac{\Delta v_i}{\Delta t} \right\rangle_{ep} f_e(\mathbf{v}) d^3 v = \frac{F_d(|\mathbf{u}_p - \mathbf{u}_e|)}{m_e}$$

Exact integral for streaming Maxwellians



Q: How do collisions affect e^- energy ?

$$\varepsilon_e = \frac{1}{2} m_e \int v^2 f_e(\mathbf{x}, \mathbf{v}) d^3\mathbf{v}$$

$$\left(\frac{\partial f_e}{\partial t} \right)_{\text{col}} = - \frac{\partial}{\partial v_j} \left[\left\langle \frac{\Delta v_j}{\Delta t} \right\rangle f_e - \frac{1}{2} \frac{\partial}{\partial v_k} \left(\left\langle \frac{\Delta v_j \Delta v_k}{\Delta t} \right\rangle f_e \right) \right] \quad \text{Initial form of F-P eq.}$$

$$\left(\frac{\partial \varepsilon_e}{\partial t} \right)_{\text{col}} = \frac{1}{2} m_e \int v^2 \left(\frac{\partial f_e}{\partial t} \right)_{\text{col}} d^3\mathbf{v} = - \frac{1}{2} m_e \int v^2 \frac{\partial}{\partial v_j} \left[\left\langle \frac{\Delta v_j}{\Delta t} \right\rangle f_e - \frac{1}{2} \frac{\partial}{\partial v_k} \left(\left\langle \frac{\Delta v_j \Delta v_k}{\Delta t} \right\rangle f_e \right) \right] d^3\mathbf{v}$$

velocity-space
integration
by parts



$$= m_e \int v_i \delta_{ij} \left[\left\langle \frac{\Delta v_j}{\Delta t} \right\rangle f_e - \frac{1}{2} \frac{\partial}{\partial v_k} \left(\left\langle \frac{\Delta v_j \Delta v_k}{\Delta t} \right\rangle f_e \right) \right] d^3\mathbf{v}$$

$$= \int m_e \left[v_j \left\langle \frac{\Delta v_j}{\Delta t} \right\rangle + \frac{1}{2} \left\langle \frac{\Delta v_j \Delta v_j}{\Delta t} \right\rangle \right] f_e d^3\mathbf{v}$$

$L_e(\mathbf{v})$

$$\left(\frac{\partial \varepsilon}{\partial t} \right)_{\text{col}} = \int L_e(\mathbf{v}) f_e d^3\mathbf{v}$$

Energy conservation

$$\left(\frac{\partial \mathcal{E}_e}{\partial t} \right)_{\text{col}} = \int L_e(\mathbf{v}) f_e d^3\mathbf{v}$$

$$L_e(\mathbf{v}) = m_e \left(v_i \left\langle \frac{\Delta v_i}{\Delta t} \right\rangle_{ee} + \frac{1}{2} \left\langle \frac{\Delta v_i \Delta v_i}{\Delta t} \right\rangle_{ee} \right) + m_e \left(v_i \left\langle \frac{\Delta v_i}{\Delta t} \right\rangle_{ep} + \frac{1}{2} \left\langle \frac{\Delta v_i \Delta v_i}{\Delta t} \right\rangle_{ep} \right)$$

$L_{ee}(\mathbf{v})$: collisions of
e⁻s w/ other e⁻s

$L_{ep}(\mathbf{v})$: collisions of
e⁻s w/ protons

Elastic
collisions:

$$\left\{ \begin{array}{l} \int L_{ee}(\mathbf{v}) f_e d^3\mathbf{v} = 0 \\ \int L_{ep}(\mathbf{v}) f_e d^3\mathbf{v} + \int L_{pe}(\mathbf{v}) f_p d^3\mathbf{v} = 0 \end{array} \right.$$

energy exchange
between e⁻s & protons

Q: Why might the collisions be inelastic?
What would that do to the above relations?

What does $D_{ij}(\mathbf{v})$ do?

$$\left(\frac{\partial f}{\partial t}\right)_{\text{col}} = -\frac{\partial}{\partial v_i} [A_i(\mathbf{v})f] + \frac{\partial}{\partial v_i} \left[D_{ij}(\mathbf{v}) \frac{\partial f}{\partial v_j} \right] = -\frac{\partial}{\partial v_i} \left\{ A_i(\mathbf{v}) \left[f - \frac{D_{ij}(\mathbf{v})}{A_i(\mathbf{v})} \frac{\partial f}{\partial v_j} \right] \right\}$$

$$A_i(\mathbf{v}) = -\frac{4\pi e^4 \Lambda n}{m^2} \frac{v_i}{v^3} \quad D_{ij}(\mathbf{v}) = \frac{4\pi e^4 \Lambda n v_{rms}^2}{m^2} \frac{\delta_{ij}}{v^3}$$

$$\frac{D_{ij}(\mathbf{v})}{A_i(\mathbf{v})} = -\frac{v_{rms}^2}{v_i} \delta_{ij}$$

$$f(\mathbf{v}) \propto \exp\left(-\frac{|\mathbf{v}|^2}{2v_{rms}^2}\right) \Rightarrow \frac{\partial f}{\partial v_j} = -\frac{v_j}{v_{rms}^2} f \quad \rightarrow \quad \left(\frac{\partial f}{\partial t}\right)_{\text{col}} = 0$$

A: It enforces 2nd law of thermodynamics:

- Maxwellian is steady solution ($v_{rms} = v_{th}$)
- Collisions do not change a Maxwellian (A_i & D_{ij} cancel out)
- D_{ij} relaxes (diffuses) $f(\mathbf{v})$ toward a Maxwellian

$$A_i(\mathbf{v}) = -\frac{4\pi e^4 \Lambda n'}{m m'} \frac{v_i}{v^3} \quad D_{ij}(\mathbf{v}) = \frac{4\pi e^4 \Lambda n' v_{rms}^2}{m^2} \frac{\delta_{ij}}{v^3} \quad v \gg v_{th}$$

each is linear in $f_{\sigma'}(\mathbf{x}, \mathbf{v})$ of target species σ'

→ decomposing into thermal & non-thermal components

$$f_{\sigma'}(\mathbf{x}, \mathbf{v}) = f_{\sigma'}^{(th)}(\mathbf{x}, \mathbf{v}) + f_{\sigma'}^{(nt)}(\mathbf{x}, \mathbf{v}), \quad n_{\sigma'}^{(th)} \gg n_{\sigma'}^{(nt)}$$

→ $A_i(\mathbf{v}) = A_i^{(th)}(\mathbf{v}) + \cancel{A_i^{(nt)}(\mathbf{v})}$ & similar for $D_{ij}(\mathbf{v})$

$$\left(\frac{\partial f}{\partial t}\right)_{col} \approx -\frac{\partial}{\partial v_i} \left\{ \left[A_i^{(th)}(\mathbf{v}) - D_{ij}^{(th)}(\mathbf{v}) \frac{\partial}{\partial v_j} \right] (f^{(th)} + f^{(nt)}) \right\} \approx -\frac{\partial}{\partial v_i} \left\{ \left[A_i^{(th)}(\mathbf{v}) - D_{ij}^{(th)}(\mathbf{v}) \frac{\partial}{\partial v_j} \right] f^{(nt)} \right\}$$

$$\left(\frac{\partial f}{\partial t}\right)_{col} = 0 \quad \text{when both are Maxwellians of same } T$$

$$A_i(\mathbf{v}) = -\frac{4\pi e^4 \Lambda n'}{m m'} \frac{v_i}{v^3} \quad D_{ij}(\mathbf{v}) = \frac{4\pi e^4 \Lambda n' v_{rms}^2}{m^2} \frac{\delta_{ij}}{v^3} \quad v \gg v_{th}$$

each is linear in $f_{\sigma'}(\mathbf{x}, \mathbf{v})$ of target species σ'

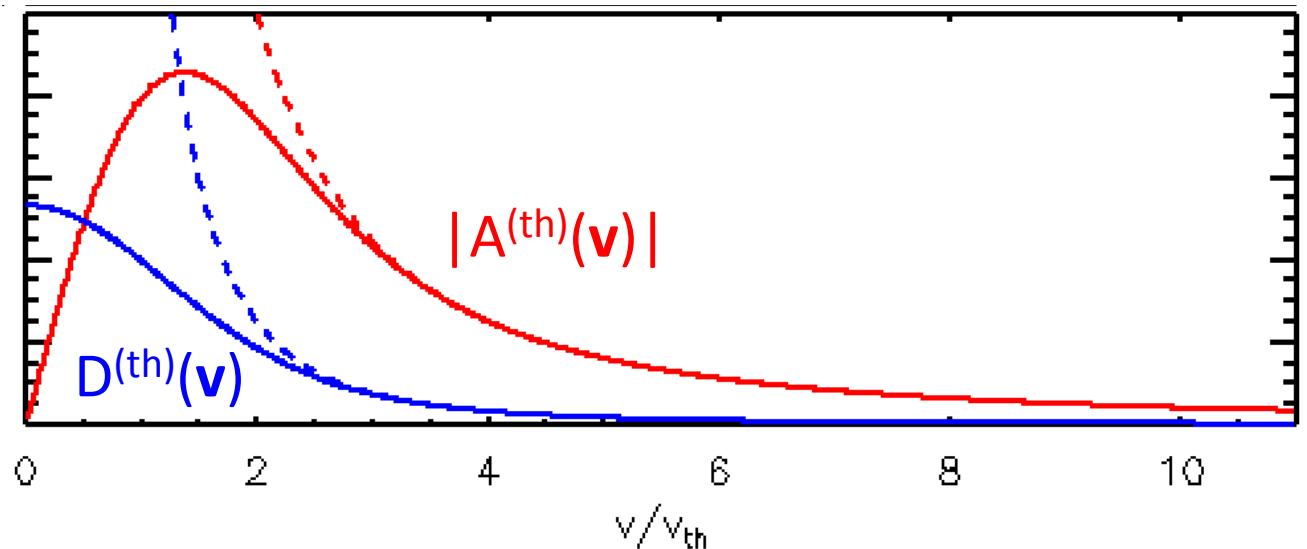
→ decomposing into thermal & non-thermal components

$$f_{\sigma'}(\mathbf{x}, \mathbf{v}) = f_{\sigma'}^{(th)}(\mathbf{x}, \mathbf{v}) + f_{\sigma'}^{(nt)}(\mathbf{x}, \mathbf{v}) \quad , \quad n_{\sigma'}^{(th)} \gg n_{\sigma'}^{(nt)}$$

→ $A_i(\mathbf{v}) = A_i^{(th)}(\mathbf{v}) + \cancel{A_i^{(nt)}(\mathbf{v})}$ & similar for $D_{ij}(\mathbf{v})$

$$\left(\frac{\partial f}{\partial t}\right)_{col} \approx -\frac{\partial}{\partial v_i} \left\{ \left[A_i^{(th)}(\mathbf{v}) - D_{ij}^{(th)}(\mathbf{v}) \frac{\partial}{\partial v_j} \right] (f^{(th)} + f^{(nt)}) \right\} \approx -\frac{\partial}{\partial v_i} \left\{ \left[A_i^{(th)}(\mathbf{v}) - D_{ij}^{(th)}(\mathbf{v}) \frac{\partial}{\partial v_j} \right] f^{(nt)} \right\}$$

→ can use the collision coefficients computed w/ Maxwellian distribution



Electron momentum eq. – *a.k.a.* Ohm's law

$$\frac{\partial f_e}{\partial t} = -\frac{\partial}{\partial x_j} (v_j f_e) - \frac{\partial}{\partial v_j} \left(\frac{F_j}{m_e} f_e \right) + \left(\frac{\partial f_e}{\partial t} \right)_{\text{col}}$$

$$\frac{\partial}{\partial t} (m_e n_e u_{e,i}) = \int m_e v_i \frac{\partial f_e}{\partial t} d^3 v = -\frac{\partial}{\partial x_j} \int m_e v_i v_j f_e d^3 v - \int v_i \frac{\partial}{\partial v_j} (F_j f_e) d^3 v + m_e \int v_i \left(\frac{\partial f_e}{\partial t} \right)_{\text{col}} d^3 v$$

$$m_e \int (v_i - u_i)(v_j - u_j) f_e d^3 v + m_e \int u_i u_j f_e d^3 v = p_{ij} + m_e n_e u_i u_j$$

Electron momentum eq. – *a.k.a.* Ohm's law

$$\frac{\partial f_e}{\partial t} = -\frac{\partial}{\partial x_j} (v_j f_e) - \frac{\partial}{\partial v_j} \left(\frac{F_j}{m_e} f_e \right) + \left(\frac{\partial f_e}{\partial t} \right)_{\text{col}}$$

$$\frac{\partial}{\partial t} (m_e n_e u_{e,i}) = \int m_e v_i \frac{\partial f_e}{\partial t} d^3 v = -\frac{\partial}{\partial x_j} \int m_e v_i v_j f_e d^3 v - \underbrace{\int v_i \frac{\partial}{\partial v_j} (F_j f_e) d^3 v}_{+ m_e \int v_i \left(\frac{\partial f_e}{\partial t} \right)_{\text{col}} d^3 v}$$

$$m_e \int (v_i - u_i)(v_j - u_j) f_e d^3 v + m_e \int u_i u_j f_e d^3 v = p_{ij} + m_e n_e u_i u_j$$

integration
by parts

$$\int \frac{\partial v_i}{\partial v_j} F_j f_e d^3 v = \int F_i f_e d^3 v = n_e \bar{F}_i = -n_e e E_i - \frac{n_e e}{c} (\mathbf{u}_e \times \mathbf{B})_i$$

Electron momentum eq. – *a.k.a.* Ohm's law

$$\frac{\partial}{\partial t} (m_e n_e u_{e,i}) = - \frac{\partial}{\partial x_j} (m_e n_e u_{e,i} u_{e,j} + p_{ij}) - m_e n_e e \left[E_i + \frac{1}{c} (\mathbf{u}_e \times \mathbf{B})_i \right] + m_e \int v_i \left(\frac{\partial f_e}{\partial t} \right)_{\text{col}} d^3 v$$

$$m_e \int \left\langle \frac{\Delta \mathbf{v}}{\Delta t} \right\rangle_{ep} f_e d^3 v \approx \frac{m_e}{e} \mathbf{v}_{ep} \mathbf{J}$$

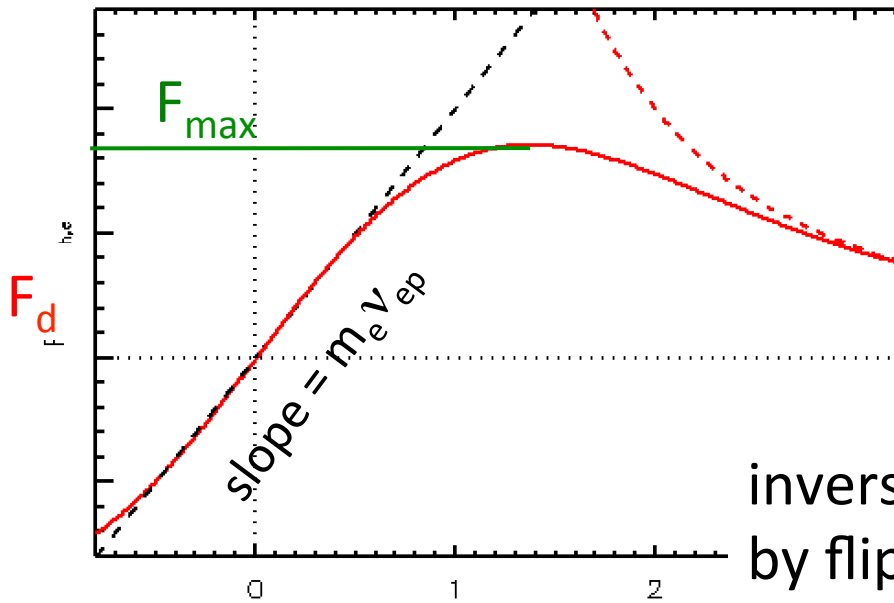
1st moment of e⁻ F-P eqn. → generalized Ohm's law η

$$m_e n_e \frac{\partial \mathbf{u}_e}{\partial t} + m_e n_e (\mathbf{u}_e \cdot \nabla) \mathbf{u}_e = -\nabla \cdot \vec{p}_e - en_e \left[\mathbf{E} + \frac{1}{c} \mathbf{u}_e \times \mathbf{B} - \frac{m_e}{e^2 n_e} \mathbf{v}_{ep} \mathbf{J} \right]$$

e-p collision coefficient $\left\langle \frac{\Delta v_i}{\Delta t} \right\rangle_{ep} \sim A_i^{(ep)}(\mathbf{v})$

= 0 in classical Ohm's law

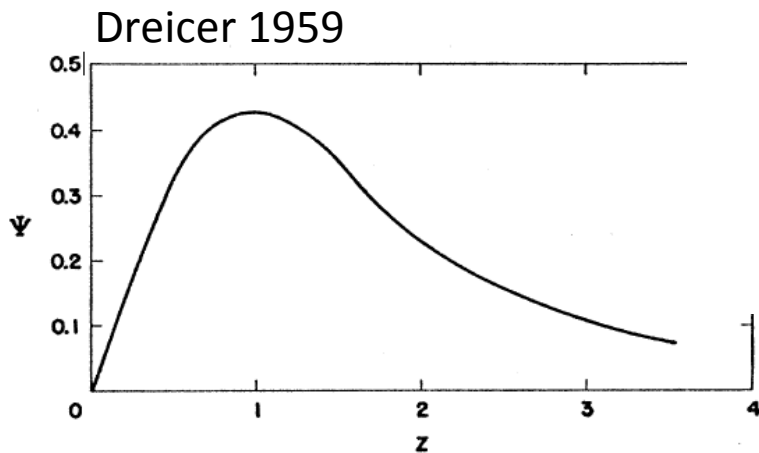
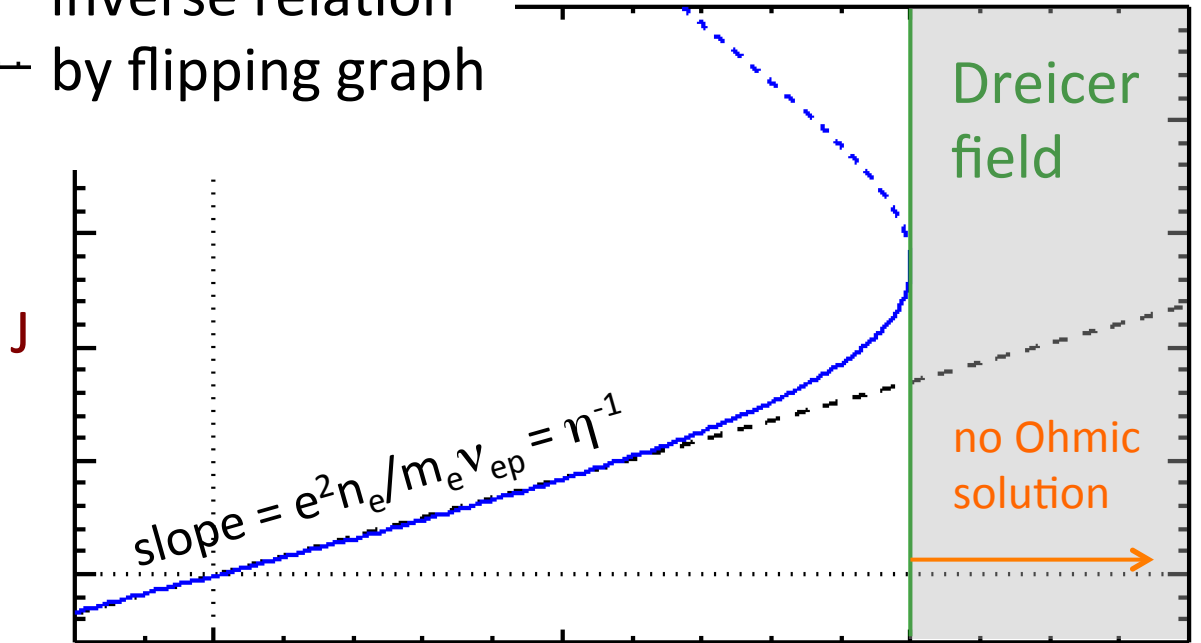
→ resistivity η



Exact integral for streaming Maxwellians

inverse relation by flipping graph

$$u_p - u_e = J / (en_e)$$



$$E_{||} = F_d / e$$

$$E_D = F_{\text{max}} / e$$

Ohm's law describes **1st moment** of **f(v)**...
Fokker-Planck eqn. describes full function

$$\frac{\partial f_e}{\partial t} + \frac{\partial}{\partial x_i} (v_i f_e) + \frac{\partial}{\partial v_i} \left(\frac{F_i}{m} f_e \right) = - \frac{\partial}{\partial v_i} [A_i(\mathbf{v}) f_e] + \frac{\partial}{\partial v_i} \left[D_{ij}(\mathbf{v}) \frac{\partial f_e}{\partial v_j} \right]$$

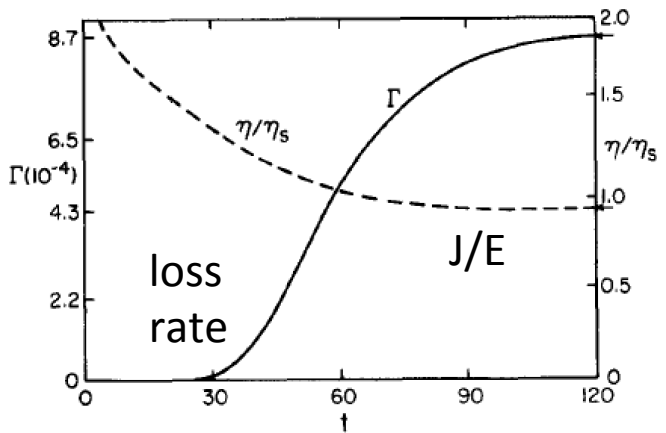
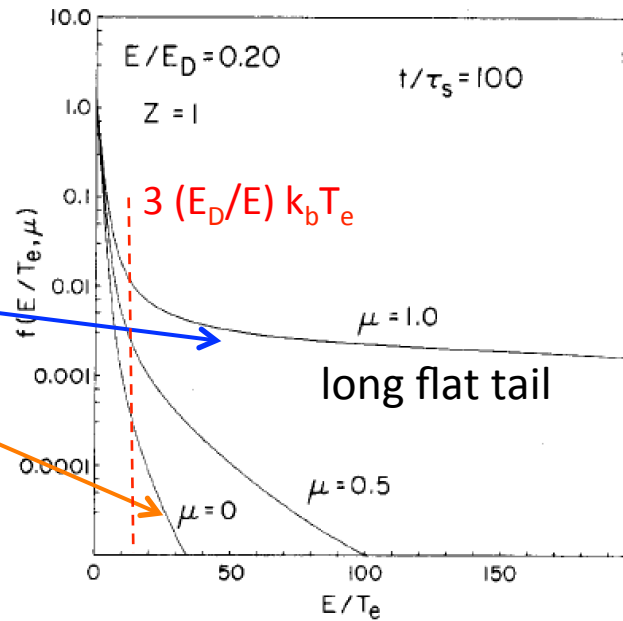
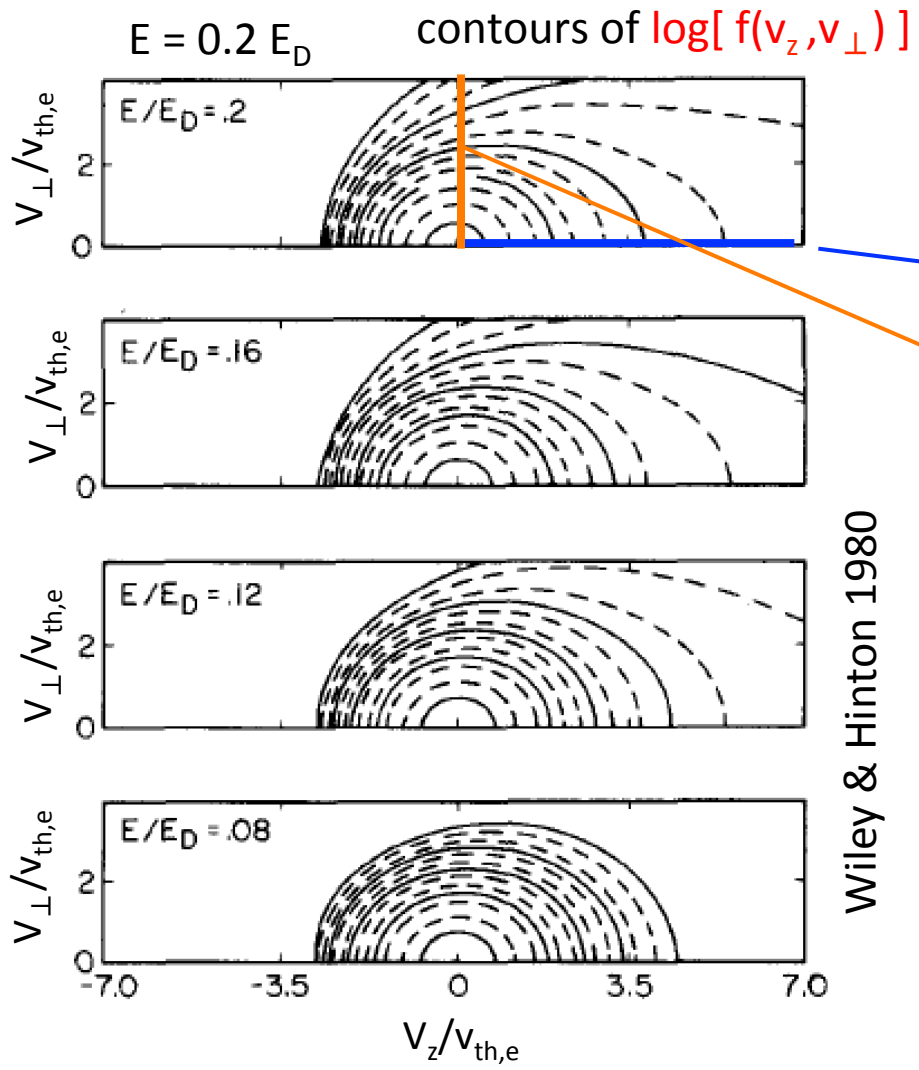
Response to E:

- idealized problem due to Spitzer & Härm (1953), Kruskal & Bernstein (1964), Kulsrud, et al. (1973)
- spatially uniform: $\nabla = 0$
- protons **retain** stationary Max'n distribution
- initialize e's w/ stationary uniform Max'n dist'n - $T_e = T_p$
- @ t=0 introduce uniform $\mathbf{E} = -E \hat{\mathbf{z}}$ w/ $E < E_D$
- solve F-P eq. for $f_e(v_z, v_{\perp}, t)$ $t > 0$

$$\frac{\partial f_e}{\partial t} = eE \frac{\partial f_e}{\partial v_z} - \frac{\partial}{\partial v_i} [A_i(\mathbf{v}) f_e] + \frac{\partial}{\partial v_i} \left[D_{ij}(\mathbf{v}) \frac{\partial f_e}{\partial v_j} \right]$$

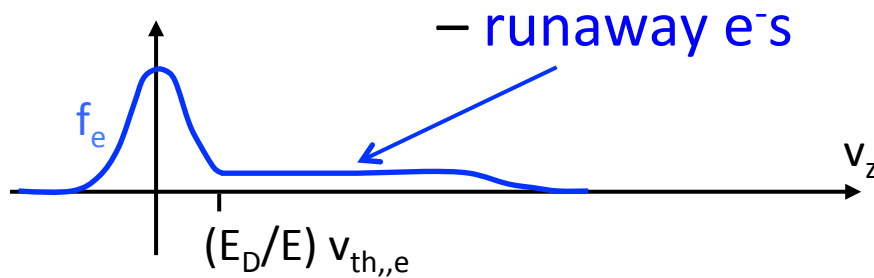
$$\frac{\partial f_e}{\partial t} = eE \frac{\partial f_e}{\partial v_z} - \frac{\partial}{\partial v_i} [A_i(\mathbf{v}) f_e] + \frac{\partial}{\partial v_i} \left[D_{ij}(\mathbf{v}) \frac{\partial f_e}{\partial v_j} \right]$$

A_i & D_{ij} from initial, Max'n, e^- & p dist'ns

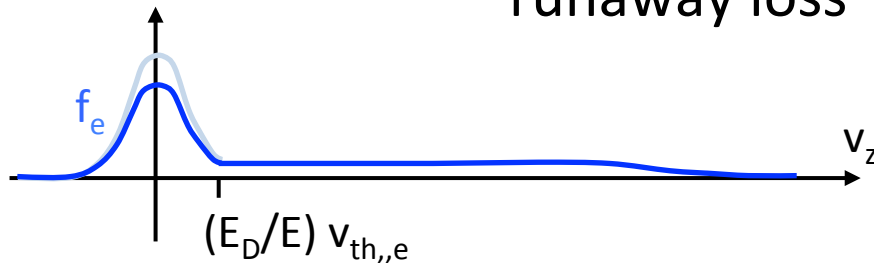


response to E:

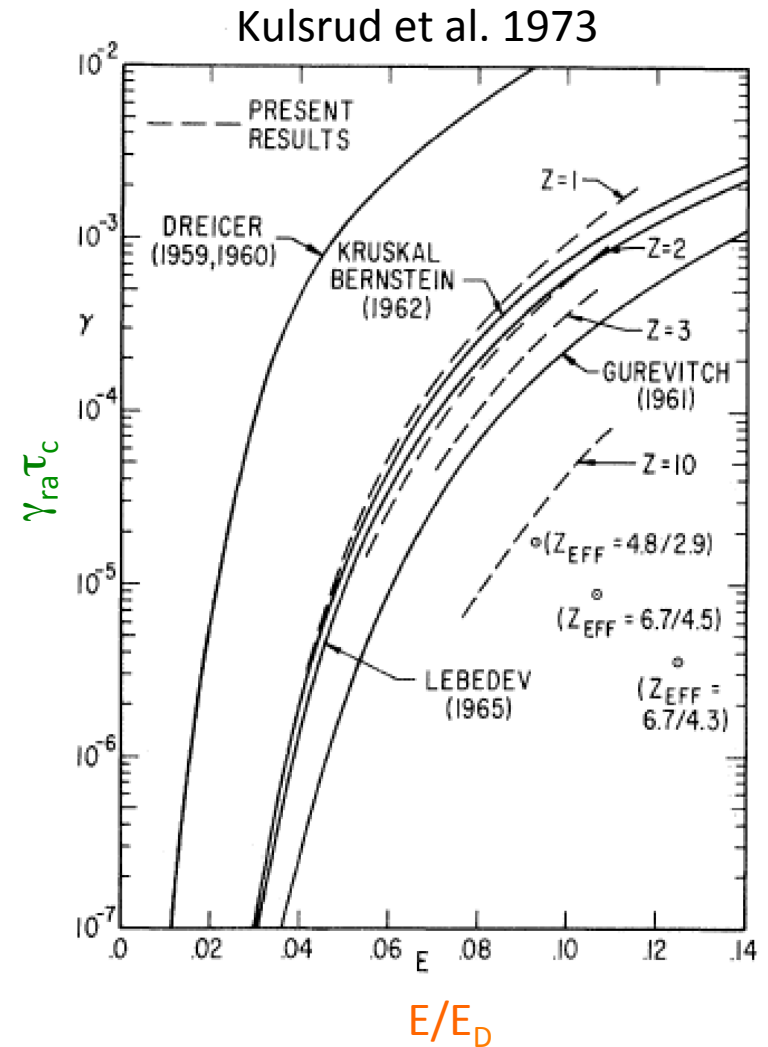
- $f_e(v_z, v_{\perp}, t)$ develops long tail



- tail grows in time
– core decreases $\sim e^{-\gamma t}$
runaway loss

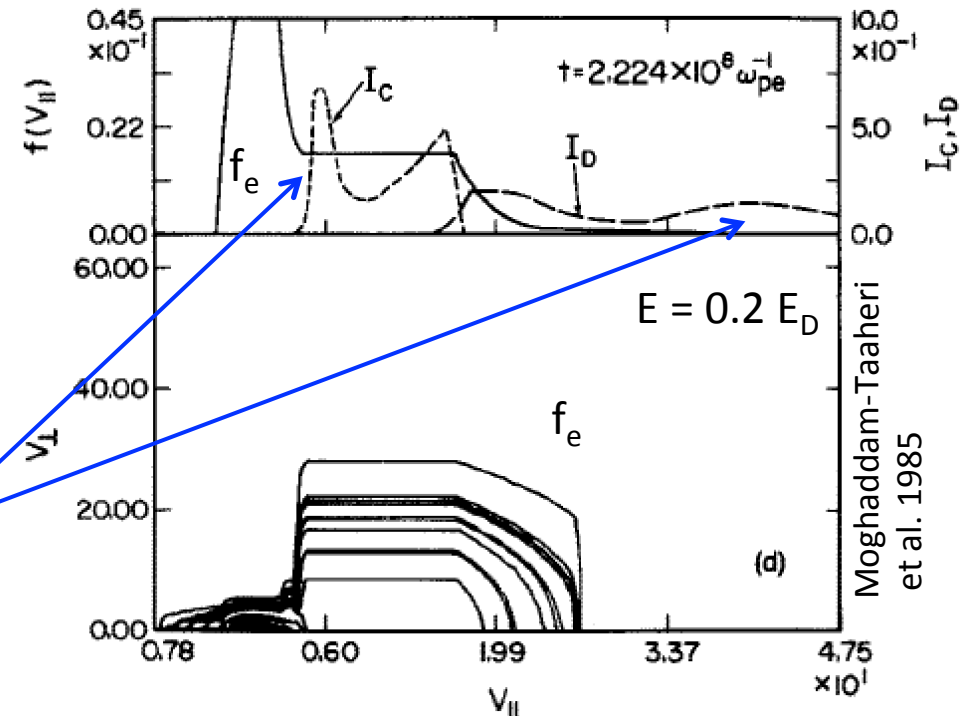
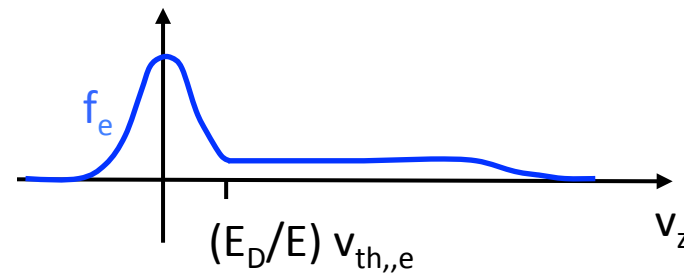


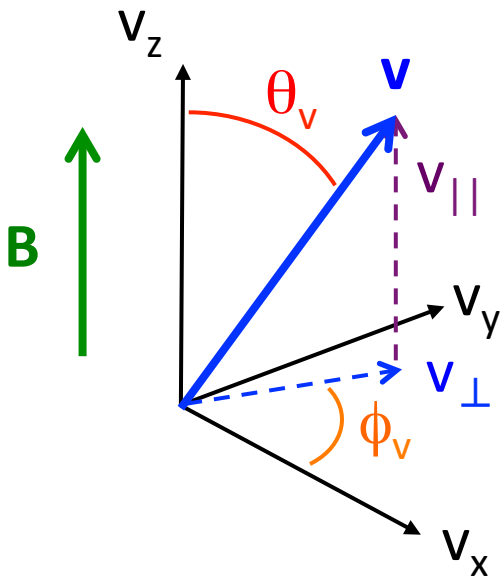
- Runaway loss rate, γ_{ra} , depends strongly on E/E_D



What this means for flares:

- tail is not a power law !?
(can use in complicated model)
- $E \ll E_D$ – lest a significant fraction of e^- s are lost
 - would leave +ve net charge in corona
 - \rightarrow large opposing E – cancel out original E
 - No longer homogeneous problem – need geometry
- dist'n w/ tail: **unstable**
 - create turbulence of plasma waves (LH \rightarrow)
 - modifies A_i & D_{ij} – more to come about this
 - all current treatments include effects of **turbulent wave spectra**





$$\mathbf{A}(\mathbf{v}) = A(v) \hat{\mathbf{v}} \quad \vec{D}(\mathbf{v}) = D(v) \vec{I}$$

gyromotion \rightarrow no dep'nce on ϕ_v

$$f(\mathbf{v}) = \frac{\tilde{f}(v, \mu)}{2\pi v^2}$$

$$\frac{\partial}{\partial \mathbf{v}} \cdot [\mathbf{A}(\mathbf{v}) f(\mathbf{v})] = \frac{1}{2\pi} \frac{1}{v^2} \frac{\partial}{\partial v} [A(v) \tilde{f}]$$

$$\frac{\partial f(\mathbf{v})}{\partial \mathbf{v}} = \frac{1}{2\pi} \left[\frac{1}{v^2} \frac{\partial \tilde{f}}{\partial v} - \frac{2}{v^3} \tilde{f} \right] \hat{\mathbf{v}} + \frac{1}{2\pi} \frac{1}{v^3} \left[\frac{d\mu}{d\theta_v} \frac{\partial \tilde{f}}{\partial \mu} \right] \hat{\theta}_v$$

$$= -\sin(\theta_v) = -\sqrt{1 - \mu^2}$$

$$\frac{\partial}{\partial \mathbf{v}} \cdot [\vec{D}(\mathbf{v}) \cdot \frac{\partial f(\mathbf{v})}{\partial \mathbf{v}}] = \frac{1}{2\pi} \frac{1}{v^2} \left\{ \frac{\partial}{\partial v} \left[D(v) \left(\frac{\partial \tilde{f}}{\partial v} - \frac{2}{v} \tilde{f} \right) \right] + \frac{D(v)}{v^2} \frac{\partial}{\partial \mu} \left[(1 - \mu^2) \frac{\partial \tilde{f}}{\partial \mu} \right] \right\}$$

Fokker-Planck equation in (v, μ) space

$$\tilde{f}(v, \mu) = 2\pi v^2 f(\mathbf{v})$$

$$\left(\frac{\partial \tilde{f}}{\partial t}\right)_{\text{col}} = -\frac{\partial}{\partial v} \left\{ \left[A(v) + \frac{2D(v)}{v} \right] \tilde{f} \right\} + \underbrace{\frac{\partial}{\partial v} \left[D(v) \frac{\partial \tilde{f}}{\partial v} \right]}_{\text{energy diffusion}} + \underbrace{\frac{D(v)}{v^2} \frac{\partial}{\partial \mu} \left[(1 - \mu^2) \frac{\partial \tilde{f}}{\partial \mu} \right]}_{\text{pitch angle diffusion}}$$

energy
diffusion

pitch angle
diffusion –
works to make f
uniform in pitch
angle cosine

→ distribution uniform over
sphere of constant v

$$\frac{\partial \tilde{f}}{\partial \mu} \rightarrow 0$$

Summary

- Distribution function $f_{\sigma}(\mathbf{x}, \mathbf{v})$ for species σ ($=e, p$) evolves by Fokker-Planck (F-P) equation
- F-P eqn. includes collisions via coefficients $A_i(\mathbf{v})$ and $D_{ij}(\mathbf{v})$
- Account for fluid effects include resistivity
- F-P shows how $f_e(\mathbf{x}, \mathbf{v})$ responds to DC \mathbf{E}

Next: How F-P can account for plasma waves –
Stochastic Acceleration